

Solving black box models with a derivative based nonlinear optimization solver

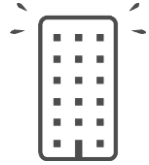
JFRO 2024

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Artelys

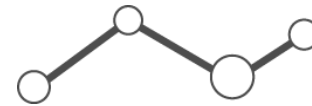
Artelys is an independent company, created in 2000, specialized in **optimization, decision-support, modeling.**



2000
CREATION
Arnaud Renaud



15% annual
sustained growth



120 EXPERTS
MSc and PhD



25% of our activity
is dedicated to **R&D**



SOFTWARE EDITION

Custom software,
off-the-shelf software,
Numerical solvers



SERVICES & CONSULTING

Optimisation,
Data Science
and business expertise

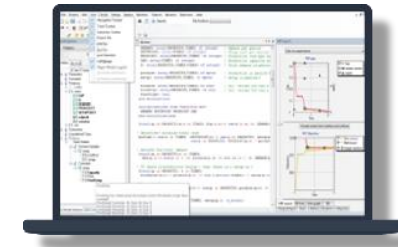


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Artelys Knitro overview

▴ Some historical background

- | Created in 2001 by Ziena Optimization
 - ↳ Spin-off of Northwestern University
- | Artelys is the worldwide distributor of Knitro since 2009
- | Artelys acquired Ziena Optimization in 2015



▴ Key features

- | **Efficient** and **robust** solution on **large scale** problems ($\sim 10^5$ variables)
- | **Four** active-set and interior-point algorithms for continuous optimization
- | **MINLP algorithms** and **complementarity constraints** for discrete optimization
- | **Many extra features** based on **customer feedbacks** or project requirements
- | Parallel multi-start method for **global optimization**.
- | Easy to use and well documented: [Online documentation](#)

Artelys Knitro problem classes solved

▴ Variables (x and y)

- | Continuous or discrete
- | Bounded or unbounded

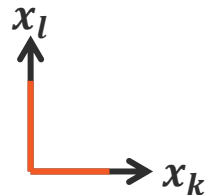
$$\begin{array}{ll} \min_{x \in \mathbb{R}^n, y \in \mathbb{Z}^m} & f(x, y) \\ \text{s.t.} & g_i(x, y) \geq 0 \quad i \in I \\ & h_j(x, y) = 0 \quad j \in J \\ & 0 \leq x_k \perp x_l \geq 0 \quad (k, l) \in C \subset \llbracket 1, n \rrbracket^2 \\ & l_x \leq x \leq u_x \\ & l_y \leq y \leq u_y \end{array}$$

▴ Objective (f) and constraints (g and h)

- | Algebraic equations available or external callback to evaluate functions (**black box**)
- | Smoothness: preferred but not required
- | Convexity: preferred but not required, local optimization or global optimization with **multistart**

▴ Complementarity constraints

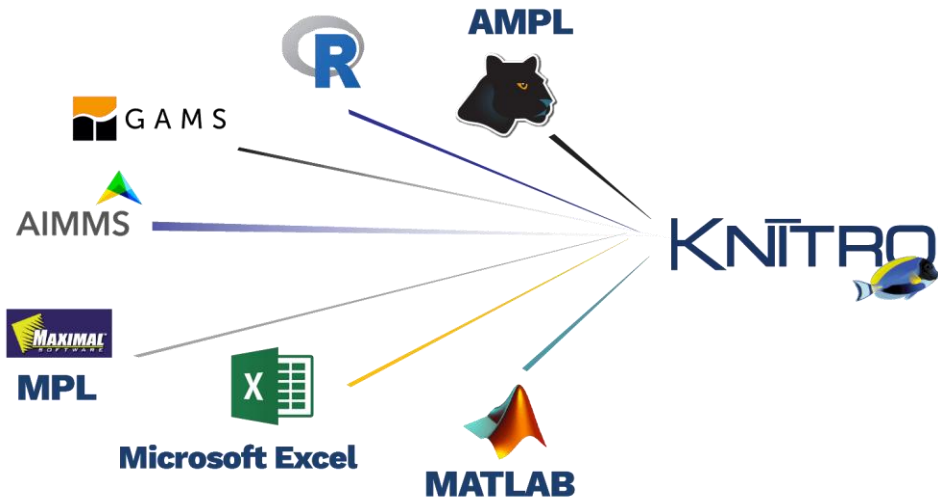
- | $0 \leq x_k \perp x_l \geq 0$ is equivalent to: $x_k \geq 0$ and $x_l \geq 0$ and $\{x_k = 0 \text{ or } x_l = 0\}$
- | Applications: strategic bidding, economic models, equilibrium constraints, disjunctions



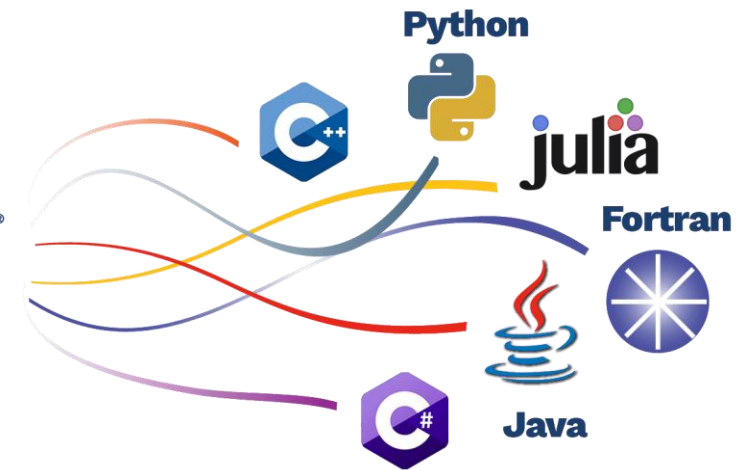
Artelys Knitro overview

Interfaces

| Modeling languages



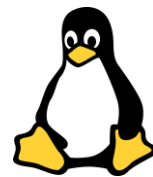
| Programming languages



Supported platforms



Windows 64-bit



Linux 64-bit



macOS 64-bit



ARM architecture

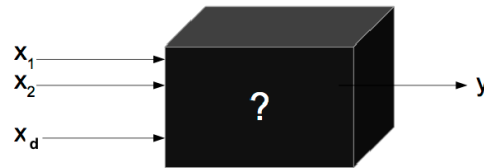
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Black box – General overview

4 Artelys Knitro is widely used to solve black box applications

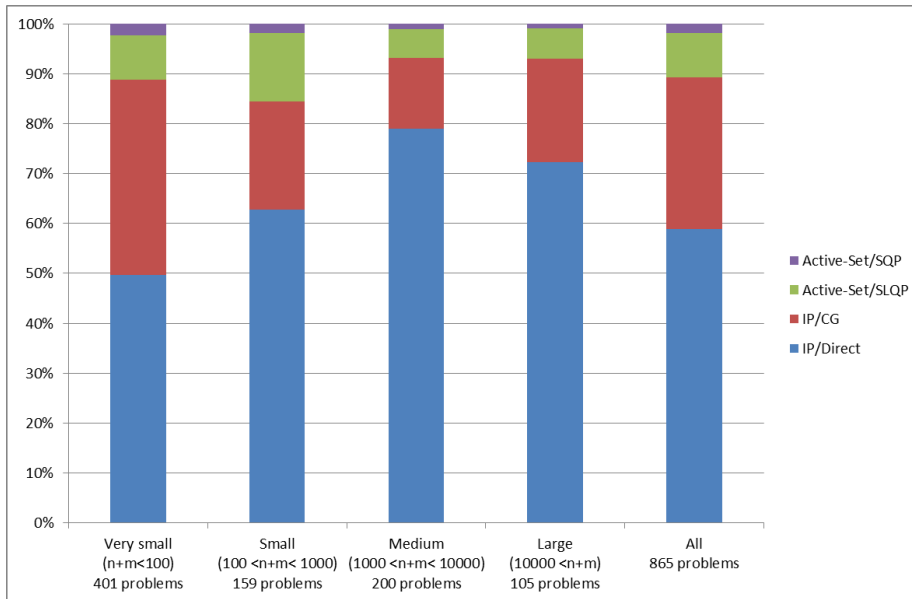
- | Grey / Black box applications arise when the algebraic equations of the optimization model is not known or only partially



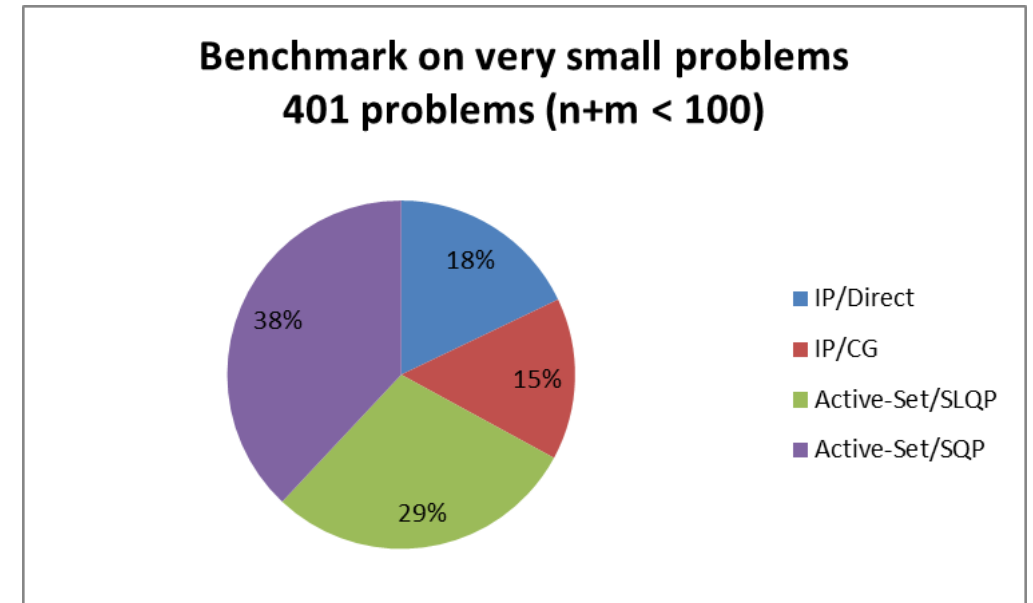
- | Most of the time the optimization relies on an **external simulator** to compute the model state
 - ↳ Blending models – oil&gas, mining industry ...
 - ↳ Finite elements computations – computer aided design (CAD), electric transformers design, structure design ...
 - ↳ Hydraulic models
 - ↳ Multi-Disciplinary Analysis and Optimization (**MDAO**)
 - Connection possible with OpenMDAO developed by Nasa
 - Major applications in spatial, aeronautics, autonomous vehicles
 - Good results obtained for industrial customers in the defense sector

Artelys Knitro algorithms comparison

4 Comparison on Artelys Knitro four different algorithms



Exact first and second order derivatives



Derivative free optimization (Black box)

4 Advantage of active set methods for black box models

- | Converge in fewer iterations (minimize the number of function evaluations)
- | Good warm start

Cost of derivative approximation (1)

4 Approximation of first derivatives by finite differences (biggest cost)

- | Good approximation necessary for the convergence of the algorithms
- | Forward or central finite differences – tradeoff that is not always obvious !
 - ↳ Central brings accuracy than can cut down iterations significantly !
- | **Automatic selection of the finite differences step** to avoid falling in the simulator noise
 - ↳ 1e-15 by default for algebraic equations, can be changed by user
 - ↳ E.g. for transformer design, changing the size of the transformer by 1e-15 is not significant
- | Can also exploit the **sparsity pattern** of the Jacobian if available.
 - ↳ Even if it is black box, not all constraints depend on all variables -> physical knowledge of the simulator
- | Ability to perform **parallel function evaluations** to compute finite differences

Cost of derivative approximation (2)

4 Approximation of the Hessian (second-order derivative)

- | These methods do **not require additional function evaluations**.
- | Improve convergence “for free” (in terms of function evaluation)

4 Possibility to pass the **known structure separately** (linear, quadratic, conic..)

- | Knitro can compute the exact derivatives of several expressions
- | Part of the model can be black box and approximated, the rest can be passed as algebraic equations
- | For example:
 - ↳ Pass linear structure directly to Knitro
 - ↳ Create one callback with nonlinear expressions for which you can pass derivatives (at least Jacobian)
 - ↳ Create one ‘black box’ callback where no derivatives can be provided

Other nice features

- ▴ **Noise estimation to allow faster convergence by analyzing the simulator precision**
 - | Automatic update of termination criteria when iteration steps reaches estimated simulator precision

- ▴ **Ability to multistart for non-convex models to use different initial points**
 - | Initial points can be provided by the user or automatically generated
 - | Specific convergence criteria to stop when probability to find a new local solution is low

- ▴ **Specific MISQP algorithm for problem with non relaxable integers**
 - | Do not rely on a B&B approach
 - | Particularly interesting for physical simulators with strong integrity constraint on parameters
 - | Mimic SQP continuous algorithm relying on a grid search for integer variables

Achievements

▴ Consistently getting good results on Black-box competition (BBCOMP) from 2016 to 2019

- | Won several single objective and multi-objective instances over the years
- | Especially on **expensive tracks** with limited function evaluation budget
- | Simple plugin of Knitro relying on the different features
 - ↳ Multi start was activated to start from different initial points
 - ↳ Management of termination criteria to avoid spending effort on low quality solves
 - ↳ For multi-objective, we recreate the “pareto front” by successively optimizing the different objectives

▴ Since we participated in BBCOMP

- | Automatic step computation of finite differences
- | Noise estimation for convergence criteria
- | Ability to pass some of the problem structure when available
- | Enhanced multistart initial point generation and termination criteria

▴ Always open to new challenges if you have any !

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Conclusion

▴ Summary

- | Artelys Knitro provides several competitive specializations for black box models
- | First order derivative approximation is the predominant cost (because of function evaluations)
- | Pass as much information as you can, it's not necessarily equations !
- | Knitro will approximate all the required information you can't provide
- | Particularly efficient for applications with strict computation budget !

▴ Future developments will continue focusing on improving Black box features

- | Automatic detection of sparsity pattern for Jacobian approximation
- | Approximate several independent Jacobian values simultaneously

Come and try it !

Free trial

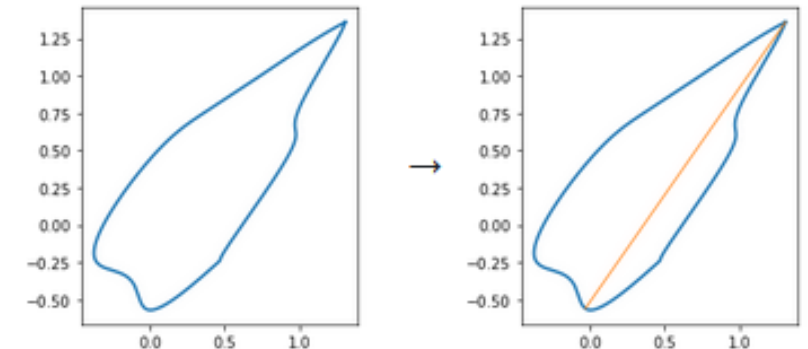
- | Directly accessible from our website

Free teaching program

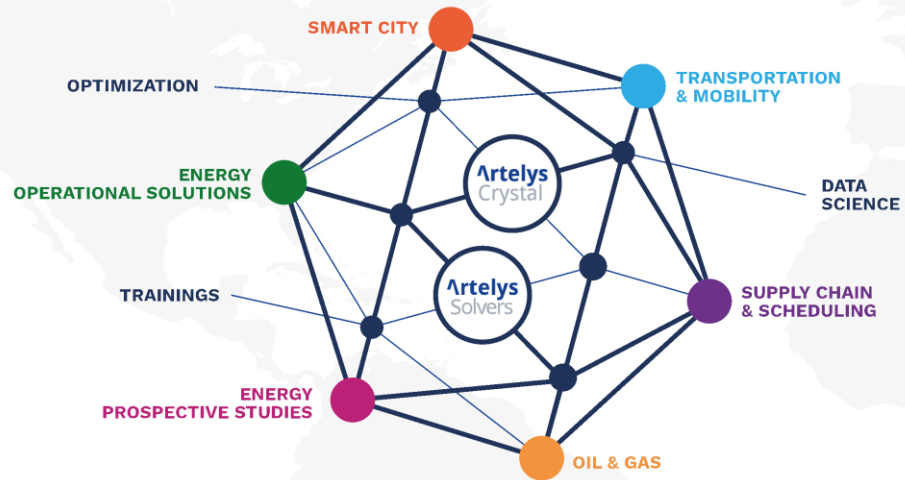
- | Free academic licenses for the professor and the students during the time of the course
- | Contact us at info-knitro@artelys.com

Checkout Artelys Knitro tutorials on Github

- | Include models both with Knitro API or modeling languages !
- | <https://github.com/Artelys/knitro-modeling-examples>



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